

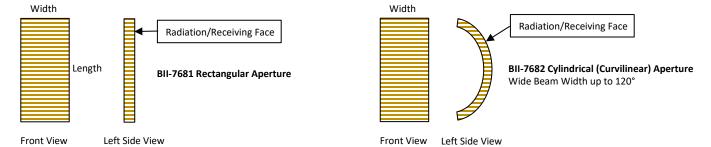
Benthowave Instrument Inc. Underwater Sound Solutions www.benthowave.com

BII-7680 Series Wide-beam Directional Transducer

BII-7680 Series Wide-beam Directional Transducer: Fan-shaped Beam

These transducers have rectangular (linear) or curvilinear (Cylindrical) apertures with custom-fit along-length (or along-curve) beamwidth and cross-length (or cross-curve) beamwidth for use in location, search of sound sources underwater in in tens or hundreds meter range, and acoustical imaging in biomedical, oceanography, NDT and material study. Multiple transducers can be wired in parallel electrically to set up a longer line array for reducing along-length beam width in low frequency range. The directional response detects the sounds from the area of interest and rejects unwanted noises coming from other directions. High resolution image can be formed with the technique of **Synthetic Aperture Imaging**.

Transducer Structure



Typical Applications

Acoustical Imaging in Biomedical, Oceanography, NDT/AE, and Material Study	Underwater Floor/Bottom Mapping, Sector Scanning, 2D Imaging
Direction-finding Sonar, Acoustic Pipeline Leak Detection	Communication, Navigation, Target Tracking, Obstacle Avoidance, Positioning

Specification

Dhand America	DU 7004	DU 7003			
Phased Array	BII-7681	BII-7682			
Array Aperture:	Rectangular Aperture	Curvilinear (Cylindrical Sector) Aperture			
Major Features:	Narrow Beam along the length.	Wide Beam along the curved face.			
Signal Type:	Wide beam along the width. Pulsed SINE, Chirp, PSK, FSK, Pulsed Square Waveform, CW, etc.				
Signal Type.					
Resonant Frequency fs:	fs in stock: 50, 60, 70, 100, 120, 150, 200, 250, 300, 350, 400, 500 kHz.				
Resoliding Frequency is.	1. Efficiency is low in the frequency range far from f _s , so it is NOT recommended to operate transducer at frequency far from f _s . 2. Transducer can operate in low power at frequency far from f _s , the input power P _i should be much less than 1% MCIP at f _s .				
Third Harmonic:	2.9fs ~ 3.2fs; Transducers can operate at 3fs.	is, the impact power 1 should be made less than 170 men at 15.			
Quality Factor Q _m :	≈ 3 to 53dB bandwidth = fs/Q _m .				
TVR:	> 160 dB μPa/V@1m @ fs. Transmitting Voltage Response.				
Radiation Sound Level SL:	SL = 20*logV _i + TVR, dB μPa@1m. Driving Voltage V _i is in unit of	M			
Admittance (G and B):	TBD, to be determined.	vrms.			
Admittance (G and b).	Horizontal (Along-length or Along-curve) Plane: 0.1° to 120°;				
-3dB Beam Width:	Vertical (Cross-length, or Cross-curve) Plane: 1° to 50°.				
Sab Beam Wiatii.	Specify with H°xV° when ordering. For example, 5°x50°, horizontal beam width 5°, vertical beam width 50°.				
Directivity Pattern:	Fan-shaped beam	an seam man o , terrical seam man ee .			
Steering Beam:	Manual scan by operator or mechanical scan with rotating device	es.			
Side Lobe Level:	≤ -15 (dB)	≤ -20 (dB)			
Driving Voltage:	1. Default: Maximum 600 Vrms. 2. TBD. To be determined with customization.				
Transducer without Impeda		3350111241011.			
Transacter Without Impeat	Pulsed Driving Signal and Duty Cycle D < 100%: Maximum V_i , $V_{imax} = V(MIPP/G_{max})$ or 600, whichever is less, in V_{rms} .				
Driving Voltage V _i at f _s :	Continuous Operation at 100% Duty Cycle: Maximum V _i , V _{imax} = V(MCIP/G _{max}), in V _{rms} .				
Driving voltage vi at is.	To achieve higher sound level, built-in impedance matching is recommended to step up driving voltage inside the transducer.				
Transducer with Impedance		commended to step up unving voltage inside the transducer.			
Transducer with impedant		7 \ in \/ 7 is impedance with Impedance Matching Unit at fs			
Driving Voltage V _i at f _s :		Pulsed Driving Signal and Duty Cycle D < 100%: $V_{imax} = V(MIPP * Z)$, in V_{rms} . Z is impedance with Impedance Matching Unit at fs. Continuous Operation at 100% Duty Cycle: Maximum V_i , $V_{imax} = V(MCIP * Z)$, in V_{rms} .			
Input Power P _i :					
MIPP at fs:	P _i = V _i ² * G. Refer to G-B Graph : G is conductance, G _{max} is maximum G at f _s . Maximum Input Pulse Power at f _s : P _i = V _i ² * G _{max} or TBD Watts, whichever is less. TBD, to be determined.				
MPW at MIPP and f _s :					
	TBD Seconds, Maximum Pulse Width at MIPP and at fs. TBD, to be determined.				
MCIP at f _s :	TDD Watts Maximum Continuous Input Down at f TDD to be	datarminad			
Harries determine mules wi	TBD Watts, Maximum Continuous Input Power at fs. TBD, to be				
·	dth, duty cycle and off-time with input pulse power (peak power)	at f _s :			
1. Determine the input puls	dth, duty cycle and off-time with input pulse power (peak power) e power (IPP, peak power) with sound intensity required by the pro	at f _s :			
 Determine the input puls Pulse Width ≤ (MIPP * MI 	dth, duty cycle and off-time with input pulse power (peak power) e power (IPP, peak power) with sound intensity required by the proPW*(120°c-T)/103°c)/IPP. T: Water Temperature in °c.	at f _s :			
 Determine the input puls Pulse Width ≤ (MIPP * MI Duty Cycle D ≤ MCIP*(120 	dth, duty cycle and off-time with input pulse power (peak power) e power (IPP, peak power) with sound intensity required by the proPW*(120°c-T)/103°c)/IPP. T: Water Temperature in °c.	at f _s :			
1. Determine the input puls	dth, duty cycle and off-time with input pulse power (peak power) e power (IPP, peak power) with sound intensity required by the proPW*(120°c-T)/103°c)/IPP. T: Water Temperature in °c.	at f _s :			
 Determine the input puls Pulse Width ≤ (MIPP * MI Duty Cycle D ≤ MCIP*(120 	dth, duty cycle and off-time with input pulse power (peak power) e power (IPP, peak power) with sound intensity required by the pro PW*(120°c-T)/103°c)/IPP. T: Water Temperature in °c. 0°c-T)/103°c)/IPP. -182 to -195 dB V/μPa @ fs. Free-field Voltage Sensitivity.	at f _s : pject. IPP MUST be less than MIPP.			
 Determine the input puls Pulse Width ≤ (MIPP * MI Duty Cycle D ≤ MCIP*(120 Off-time ≥ PW*(1-D)/D. 	dth, duty cycle and off-time with input pulse power (peak power) e power (IPP, peak power) with sound intensity required by the proposed power (IPP, peak power) with sound intensity required by the proposed power (IPP, peak power) with sound intensity required by the proposed power (IPP, T: Water Temperature in °c. 0°c-T)/103°c)/IPP. -182 to -195 dB V/ μ Pa @ fs. Free-field Voltage Sensitivity. Sensitivity Loss over extension cable at $f_s(dB) = 20 * \log B$	at f_s : oject. IPP MUST be less than MIPP. $\frac{1}{4\pi} \left\{ (1+2\pi f_s C_c/B)/\sqrt{[G^2+(B+2\pi f_s C_c)^2]/(G^2+B^2)} \right\}$			
 Determine the input puls Pulse Width ≤ (MIPP * MI Duty Cycle D ≤ MCIP*(120 Off-time ≥ PW*(1-D)/D. 	dth, duty cycle and off-time with input pulse power (peak power) e power (IPP, peak power) with sound intensity required by the pro PW*(120°c-T)/103°c)/IPP. T: Water Temperature in °c. 0°c-T)/103°c)/IPP. -182 to -195 dB V/μPa @ fs. Free-field Voltage Sensitivity.	at f_s : oject. IPP MUST be less than MIPP. $\{(1+2\pi f_s C_c/B)/\sqrt{[G^2+(B+2\pi f_s C_c)^2]/(G^2+B^2)}\}$ ension Cable. Cable is of 100 pF/meter roughly.			



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Mounting Options:	1. Default: Free Hanging (FH) 2. Thru-hole Mounting with Single O-ring (THSO) 3. Thru-hole Mounting with Double O-ring (THDO) 4. Bolt Fastening Mounting (Stainless Steel): (BFMSS) 5. End-face Mounting: (EFM) Please refer to online document AcousticSystem.pdf for a complete list of Mounting Options and more details.						
Cable-Out:	By default, the cable goes out of the device from the end face. To save space and have the device shorter, the cable can go out of the device from the side wall for uses in air or shallow water (< 50m). Specify when ordering.						
Cable:	1. Two Conductor Shielded Cable (SC), Rubber or PVC Jacket. 2. 50 Ω RG58 Coax (RG58) 3. 50 Ω RG174/U Coax (RG174) 4. 50 Ω RG178/U Coax (RG178) (Operating Temperature Range: -70°C To +200°C) 5. Shielded Cable with Twisted Pair and Teflon (PTFE) Jacket, ΦD=3.2 mm (SC32), up to 200°C, AWG26 Conductors. 6. Shielded Cable with Twisted Pair and Teflon (PTFE) Jacket, ΦD=4.0 mm (SC40), up to 200°C, AWG20 Conductors. Handling: Do not use the cable to support transducer weight in air and water if the transducer has a mounting part. Do not bend the cable.						
Cable Length:	1. Default: 1m. 2. Custom						
Connector:	 Default: Wire Leads (WL) Male BNC (BNC) (Max. Diameter Φ14.3 mm) SMA (Plug, Male Pin) (SMA), Voltage Rating: 335 VRMS Continuous. (Max. Diameter Φ9.24 mm) SMC (Plug, Female Socket) (SMC), Voltage Rating: 335 VRMS Continuous. (SMC) (Max. Diameter Φ6.4 mm) MIL-5015 Style (pin) (5015) (Max. Diameter Φ30 mm with 3 contacts) LEMO (Plug Male Pins) (LEMO) (Max. Diameter Φ9.5 mm with 3 contacts) Underwater Mateable Connector (pin) (UMC) (Max. Diameter Φ21.5 to Φ35 mm) Customized, buyer specifies the connector. (Custom) Note: Underwater Mateable Connector is for uses underwater. Other connectors and wire leads are for dry uses and are not waterproofed. 						
Size:		ned with customization.					
Weight:		ned with customization.					
Operation Temperature:	1. Default: -10 to +60 °C, or 14 to 140 °F. 2. Customized High Temperature Transducer: -15°C to 120°C or 5°F to 248°F.						
Storage Temperature:	-20 °C to +60 °C or -	4 °F to 140 °F.					
Impedance Matching:	BII-6000 Bespoke Impedance Matching between transducers and power amplifiers. Order Separately. Append IM to the part number for integrating BII-6000 in the transducer, and specify impedance in Ω . For example, BII-xxxxIM50 Ω : BII-xxxx transducer with built-in Impedance Matching unit as a 50 Ω load.						
TR Switch:	BII-2100 Transmittir	ng & Receiving Switch. Not Ir	ncluded. Order Separately, A	ppend TR to part number (BII-)	xxxxTR).		
Temperature Sensor:	2. Built-in temperat			tegrating a temperature senso			
		Vires shall be insulated for sa	afety. DO NOT TOUCH THE W	IRES BEFORE THE DRIVING SIG	SNAL IS SHUT DOWN.		
Cable shield must be ground			the (ferrels) DNC ski 11 ft	harden barren de Gard	and the second second		
				the signal source is firmly ground			
Transducer Wiring:	Shielded Cable	Coax/BNC/SMA/SMC	Coax/Wire Leads	Ild use at voltages above 30Va Underwater Connector	MIL-5015 Connector		
Driving Signal	White or Red	Center Contact	Coax Center Conductor	Contact 2	Contact C		
	Black	Shield	Coax Shield	Contact 2 Contact 1	Contact B		
Signal Common							
Shielding & Grounding	Shield	Shield	Coax Shield	Contact 3	Contact A		

How to Order

now to Order							
Transducer	/fs	-Beam Width	-Mounting	-Cable Length	-Cable	-Connector	
BII-7681, BII-7682	in kHz	H°xV° at fs	Refer to specs.	in meter	Refer to specs.	Refer to specs.	
Example of Part Number: Description							
BII-7681/100kHz-3°x30°-FH-10m-SC-WL BII-7681 transducer, fs: 100kHz: -3dB Beamwidth at fs: 3°x30°: Free Hanging, 10m Shielded Cable, Wire leads.							



315°

225

BII-7681

BII-7682

180°

5dB/Division

135°

270°

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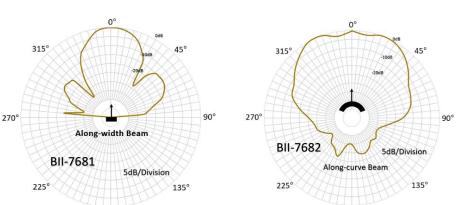
Along-curve Beam Pattern

180

Directivity Pattern: illustration ONLY. Please refer to -3 dB beam width of a specific transducer. Along-length Beam Pattern

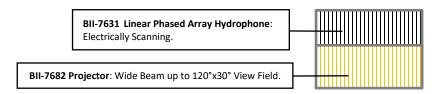
90°

Along-width or Along-height Beam Pattern

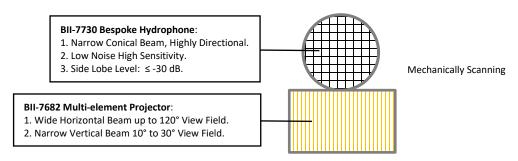


2D Imaging Multibeam Transducer: one BII-7631 Linear Phased Array (Rectangular Aperture) and one BII-7682 (Curvilinear or Cylindrical Sector Aperture).

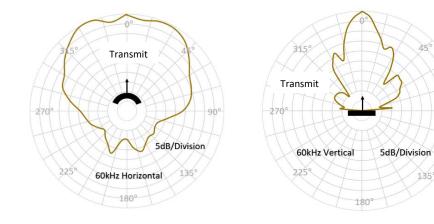
180°



Echo-ranging or Scanning Transducer: one BII-7682 (Curvilinear or Cylindrical Sector Aperture) projector and one bespoke BII-7730 Hydrophone.



Echo Ranging Transducer, typical directivity Pattern. Illustration ONLY at 60 kHz. **Transmit Beam Pattern**



Receive Conical Beam Pattern

